

# Table of contents

<b>1.0</b>	<b>Considerations and charts</b> .....	1
1.1	General .....	1
1.2	What you will learn .....	2
1.3	Challenging conditions and unfamiliar waters.....	2
1.4	Chart types and scales .....	3
	1.4.1 Mercator projection .....	3
	1.4.2 Polyconic projection .....	5
	1.4.3 Gnomonic projection .....	6
	1.4.4 Scales .....	7
1.5	IALA Maritime buoyage system .....	8
1.6	Extended cruising considerations .....	8
	1.6.1 Accuracy vs. precision .....	9
	1.6.2 Chart accuracy .....	9
	1.6.3 Compass considerations .....	10
	1.6.4 Considerations for longer cruises .....	11
1.7	Sample cruise .....	11
1.8	Digital charts .....	11
	1.8.1 Raster charts .....	12
	1.8.2 Vector charts.....	13
	1.8.3 Digital chart accuracy .....	14
	1.8.4 Viewability issues .....	15
	Homework Questions .....	16
<b>2.0</b>	<b>Electronic navigation tools</b> .....	19
2.1	General .....	19
2.2	What you will learn .....	20
2.3	Electronic navigation systems .....	20
	2.3.1 System components .....	21
	2.3.2 Interface standards .....	23
2.4	Chartplotter applications and features .....	24
2.5	Computer navigation applications and features.....	26
2.6	Other hardware supporting navigation applications .....	27
2.7	Pros and cons of chartplotters versus PC-based navigation systems .....	27
	2.7.1 Cruising conditions .....	28
	2.7.2 Power and interconnection needs .....	29
	2.7.3 Budget and future plans .....	29
2.8	Sensors and other instrumentation .....	30
2.9	GPS .....	30
2.10	Radar .....	30
	2.10.1 Radar accuracy.....	31

2.10.2	Electronic bearing line (EBL)	33
2.10.3	Variable range marker (VRM)	33
2.10.4	Rules of relative motion	34
2.10.5	Broadband radar	35
2.10.6	Heading sensor	35
2.11	AIS receiver/transponder	35
2.12	Depth sounders and sonars	36
2.12.1	Types of depth sounders	37
2.12.2	Scanning sonar	37
2.12.3	Navigating with a depth sounder	38
2.13	Other sensors	38
2.13.1	Wind instruments	38
2.13.2	Speed, water temperature and engine sensors	39
2.14	Autopilots	39
2.14.1	What autopilots do	39
2.14.2	How autopilots work	40
2.14.3	Autopilot advantages	40
2.14.4	Responsibilities of the navigator	40
2.15	VHF radio and digital selective calling	40
2.16	Planning and systems issues	41
	Homework Questions	43
<b>3.0</b>	<b>Fixes</b>	<b>45</b>
3.1	General	45
3.2	What you will learn	45
3.3	Dead Reckoning (DR)	46
3.4	Fixes from bearings	46
3.4.1	Bearing errors	48
3.5	Running Fixes	49
3.6	Classroom exercise	55
3.7	GPS fix accuracy	55
3.8	Radar	56
3.8.1	Obtaining a fix	56
3.8.2	Radar return characteristics	58
3.8.3	Examples	59
3.8.4	Fix accuracy	60
3.9	Classroom exercise	61
	Homework Questions	62
<b>4.0</b>	<b>Avoidance techniques</b>	<b>65</b>
4.1	General	65
4.2	What you will learn	65
4.3	Pre-qualifying a boating area	66

4.4	Danger bearings .....	67
4.5	Exercise 4.1 Danger bearing – visible landmark and GPS .....	70
4.6	Crosstrack error .....	70
4.7	Danger circles .....	71
4.8	Exercise 4.2 Danger circles .....	73
4.9	Collision bearings .....	74
4.10	Putting it all together.....	75
4.11	Other techniques using GPS .....	76
4.12	Other techniques using radar .....	78
4.13	Exercise 4.3 Radar avoidance .....	78
4.14	Computer navigation using safe and avoidance areas.....	78
	Homework Questions .....	82
<b>5.0</b>	<b>Positioning techniques.....</b>	<b>83</b>
5.1	General .....	83
5.2	What you will learn .....	83
5.3	Plotting position .....	84
	5.3.1 Plotting GPS bearing and distance to a waypoint.....	85
	5.3.2 Exercise 5.1: Plotting position using bearing and distance .....	85
	5.3.3 Plotting using GPS bearings on two waypoints.....	86
	5.3.4 Plotting using GPS distances from two waypoints .....	86
	5.3.5 Plotting using two radar EBL (Electronic Bearing Lines) .....	86
	5.3.6 Plotting using radar VRM (Variable Range Marker) .....	87
	5.3.7 Plotting position using grid line crossing.....	87
5.4	Using GPS on the water.....	87
	5.4.1 Leading lines .....	87
5.5	Using radar on the water.....	87
	5.5.1 Exercise 5.2: Plotting position using radar distance off .....	89
5.6	Navigating into the wind and waves.....	89
5.6.1	Making the mark .....	90
	Homework Questions .....	91
<b>6.0</b>	<b>Working with tides .....</b>	<b>93</b>
6.1	General .....	93
6.2	What you will learn .....	93
6.3	Tides.....	93
	6.3.1 Moon phases and tides .....	94
	6.3.2 Local tide patterns.....	94
6.4	Tidal definitions .....	96
6.5	Tidal datum.....	97
6.6	Sources of tidal data.....	97
6.7	Canadian tide and current tables .....	98
	6.7.1 Tables 1 and 2: Reference Ports .....	98

6.7.2	Table 3: Secondary Ports: Information and Tidal Differences .....	98
6.7.3	Table 4: Reference and Secondary Current Stations .....	98
6.7.4	Tables 5 and 5A: Time Intervals—Height Differences .....	98
6.7.5	Daily Tables – Reference Ports and Stations.....	98
6.8	Use of the tide tables .....	99
6.8.1	Example 1: To find the height of tide at a specific place and time .....	99
6.8.2	Example 2: To find the time of a specific height of tide, at a specific location .....	105
6.9	US tide tables .....	107
6.10	Caution for boaters .....	108
	Homework Questions .....	109
<b>7.0</b>	<b>Working with tidal currents .....</b>	<b>111</b>
7.1	General .....	111
7.2	What you will learn .....	111
7.3	Tidal currents .....	111
7.4	Canadian current tables.....	112
7.5	Current solutions .....	112
7.5.1	Example 1: To find times of current turn and current maximum at a specific location .....	112
7.6	Duration of slack.....	115
7.6.1	Explanation of table .....	116
7.6.2	Example 2: To find the length of time that the current will be near slack for a specific location, time and date when ebb and flood currents are approximately equal .....	116
7.6.3	Example 3: To find the times on either side of slack water, on a certain day and at a specific location, when the current will be below a certain speed. In this example the differences between maximum flood and ebb currents are significantly different. ....	117
7.7	Velocity of current at any time .....	119
7.7.1	Example 4: To estimate the current at a time intermediate between slack and maximum flow. ....	119
7.8	Quick check to estimate current – the 50/90 rule .....	121
7.9	US current tables .....	121
7.9.1	Table 1: Current station data .....	121
7.9.2	Table 2: Current differences and other constants .....	121
7.9.3	Table 3: Interval between slack and maximum current .....	122
7.9.4	Table 4: Slack interval for current less than 0.5 knots.....	122
7.10	Caution for boaters .....	122
	Homework Questions .....	123

<b>8.0</b>	<b>Piloting with winds and currents</b> .....	125
8.1	General .....	125
8.2	What you will learn .....	125
8.3	Understanding vectors .....	125
8.4	Determine current set and drift .....	128
	8.4.1 Example – Graphical approach.....	128
	8.4.2 Exercise 8.1: Determine set and drift.....	131
8.5	Determine course to steer .....	132
	8.5.1 Method 1: Determining course to steer based on fixed boat speed through the water .....	133
	8.5.2 Method 2: Determining course to steer based on fixed boat speed .....	136
8.6	Using GPS to stay on course .....	140
	Homework Questions .....	141
<b>Appendix A</b>	.....	I
	Exercise 1 – Introductory cruise .....	I
	Solution to Exercise .....	III
<b>Appendix B</b>	.....	IV
	Cruise of the AyPee.....	IV
<b>Appendix C</b>	.....	XI
	Tide table references.....	XI
<b>Appendix D</b>	.....	XXI
	Tidal current table references .....	XXI
<b>Appendix E</b>	.....	XXXI
	Exercise 1 – Homework answers .....	XXXI
	Section 1.0 – Considerations and charts .....	XXXI
	Section 2.0 – Electronic navigation tools .....	XXXI
	Section 3.0 – Fixes .....	XXXI
	Section 4.0 – Avoidance techniques .....	XXXI
	Section 5.0 – Positioning techniques .....	XXXI
	Section 6.0 – Working with tides .....	XXXI
	Section – 7.0 Working with tidal currents .....	XXXIII
<b>Appendix F</b>	.....	XXXIV
	Cruise answers .....	XXXIV
<b>Index</b>	.....	XXXV